

INFORMATION DISCLOSURE CITATION

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(Use several sheets if necessary)

Applicant(s): Shuuji KAJITA et al.

PAGE 1 of 1
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Filing Date: May 25, 2005

Group Art Unit: 3664 3664

U.S. PATENT DOCUMENTS

| *Examiner Initial | Document Number | Date | Name | Class | Sub Class | Filing Date |
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FOREIGN PATENT DOCUMENTS

| Document Number | Date | Country | Class | Sub Class | <u>Translation</u> YES NO |
|--------------------|---------------|---------|-------|--------------|------------------------------|
| 10-86081 | April 7, 1998 | Japan | | | Abstract |
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OTHER DOCUMENTS (Including Author, Title, Date, Pertinent Pages, Etc.)

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| | Takanishi: Biped Walking Robot Compensating Moment by Trunk Motion, Journal of the Robotics Society of Japan, Vol. 11, No. 3, pp. 348-353 (1993). |
| | Nishiwaki, Kitagawa, et al.: Fast Generation of a Dynamically Stable Trajectory of Humanoid with Linear Decoupling and discretization of ZMP Derivation – attained in Perception-Action Integrated Whole-Body Humanoid H6, The 18th Annual Conference of the Robotics Society of Japan, pp. 721-72 (2000). |
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Examiner /Mcdieunel Marc/

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Examiner: Initial if reference considered, whether or not citation is in conformance with MPEP 609; draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.